

# FXyBx 2 axes

● Arm type ● Whipover

## Ordering method

**FXyBx - S**

Model	Cable	Combination	X-axis stroke	Y-axis stroke	Cable
A1			15 to 95cm	15 to 55cm	3L: 3.5m
A2					5L: 5m
A3					10L: 10m
A4					

**RCX320-2**

Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Vision System	Absolute battery
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Specify various controller setting items. RCX320 ▶ **P.660**

**RCX222**

Controller	Usable for CE	I/O selection 1	I/O selection 2
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Specify various controller setting items. RCX222 ▶ **P.670**

## Specification

	X-axis	Y-axis
<b>Axis construction</b> <small>Note 1</small>	B10	-
<b>AC servo motor output (W)</b>	100	100
<b>Repeatability</b> <small>Note 2</small> (mm)	+/-0.04	+/-0.04
<b>Drive system</b>	Timing belt	Timing belt
<b>Ball screw lead</b> <small>Note 3</small> (Deceleration ratio) (mm)	Equivalent to lead 25	Equivalent to lead 25
<b>Maximum speed (mm/sec)</b>	1875	1875
<b>Moving range (mm)</b>	150 to 950	150 to 550
<b>Robot cable length (m)</b>	Standard: 3.5 Option: 5,10	

Note 1. Use caution that the frame machining (installation holes, tap holes) differs from single-axis robots.  
 Note 2. Positioning repeatability in one direction.  
 Note 3. Leads not listed in the catalog are also available. Contact us for details.

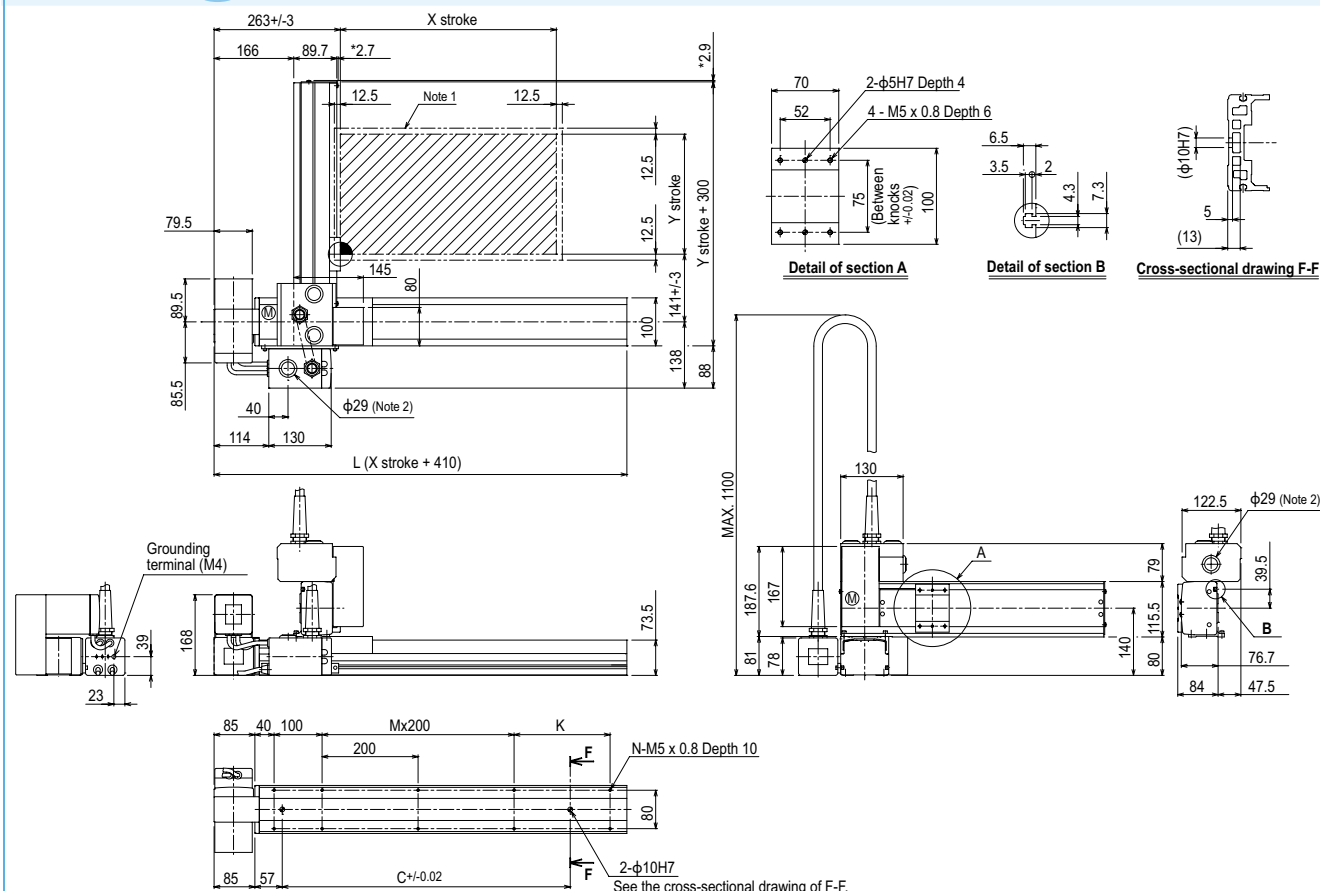
## Maximum payload (kg)

Y stroke (mm)	XY 2 axes
150	7
250	6
350	5
450	5
550	3

## Controller

Controller	Operation method
RCX320	Programming / I/O point trace / Remote command / Operation using RS-232C communication
RCX222	

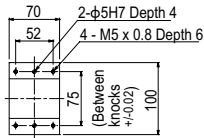
## FXyBx 2 axes A1



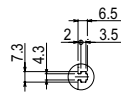
X stroke	150	250	350	450	550	650	750	850	950
L	560	660	760	860	960	1060	1160	1260	1360
C	240	420	600	600	780	780	960	960	1140
K	100	200	100	200	100	200	100	200	100
M	1	1	2	2	3	3	4	4	5
N	8	8	10	10	12	12	14	14	16
Y stroke	150	250	350	450	550				

Note 1. The moving range when returning to origin and the stop position when stopping by the mechanical stopper.  
 Note 2. User cable extraction port.  
 Note 3. The dimension marked with an asterisk (\*) indicates the height of the screw.

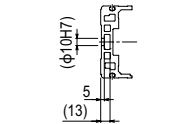
**FXYBx 2 axes A2**



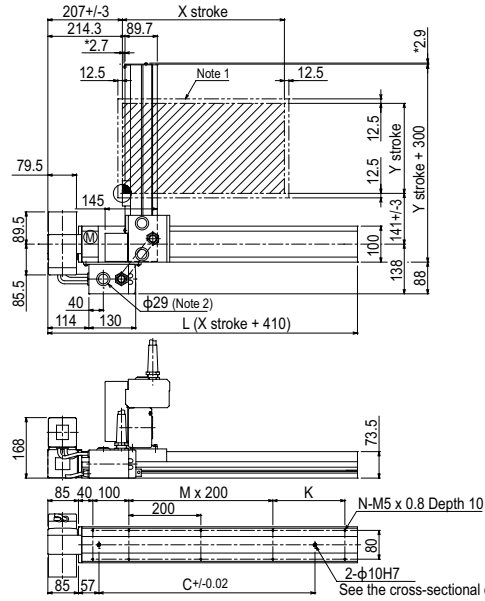
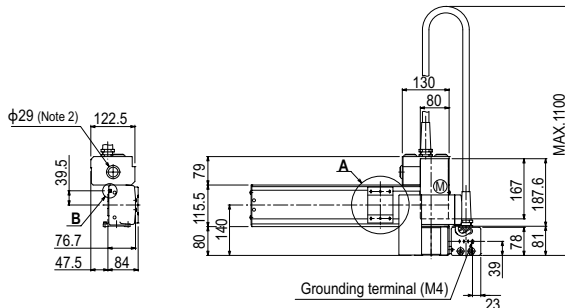
**Detail of section A**



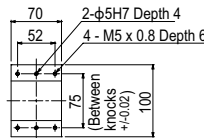
**Detail of section B**



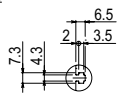
**Cross-sectional drawing F-F**



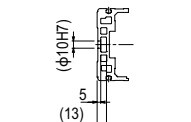
**FXYBx 2 axes A3**



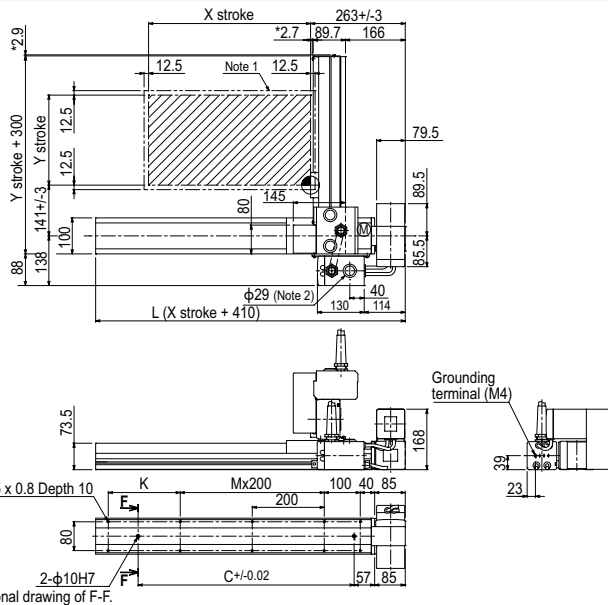
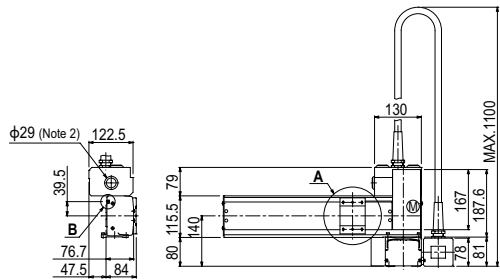
**Detail of section A**



**Detail of section B**

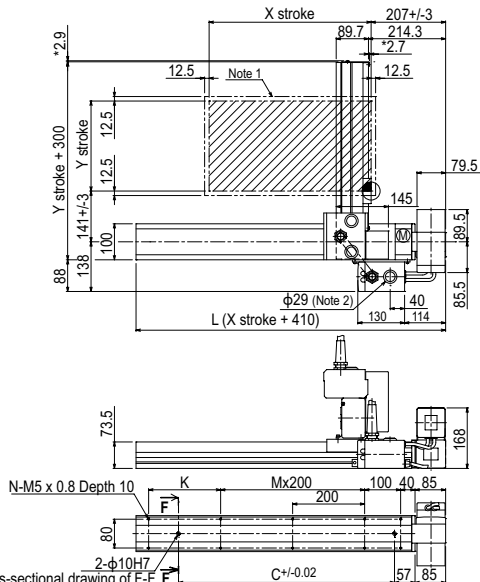


**Cross-sectional drawing F-F**

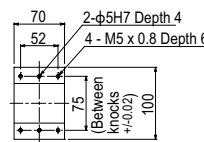


See the cross-sectional drawing of F-F.

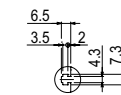
**FXYBx 2 axes A4**



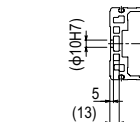
See the cross-sectional drawing of F-F.



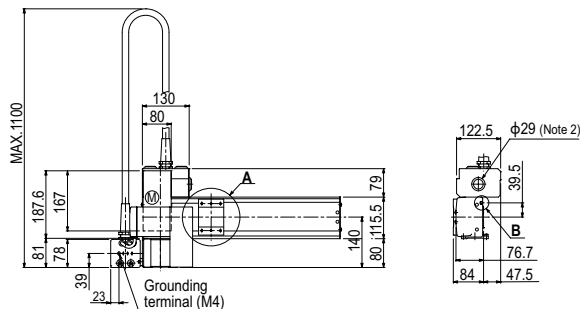
**Detail of section A**



**Detail of section B**



**Cross-sectional drawing F-F**



- Articulated robots **YA**
- Linear conveyor modules **LCM**
- Single-axis robots **CX**
- Motor-less single axis actuator **Robotomy**
- Compact single-axis robots **TRANSERO**
- Single-axis robots **FLIP-X**
- Linear motor single-axis robots **PHASER**
- Cartesian robots **XY-X**
- SCARA robots **YK-X**
- Pick & place robots **YP-X**
- CLEAN**
- CONTROLLER**
- INFORMATION**
- Arm type
- Gantry type
- Moving arm type
- Pole type
- XZ type