YK220XC

Clean type: Extra small type

Note. Built-to-order product. Contact us for the delivery period.

- Arm length 220mm
- Maximum payload 1kg

Ordering method

YK220XC - 100 - [ ] - RCX340-4 - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Model	Z axis stroke	Cable length	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
YK220XC	100: 100mm	3L: 3.5m 5L: 5m 10L: 10m	RCX340-4							

Specify various controller setting items. RCX340 ▶ P.678

Basic specifications

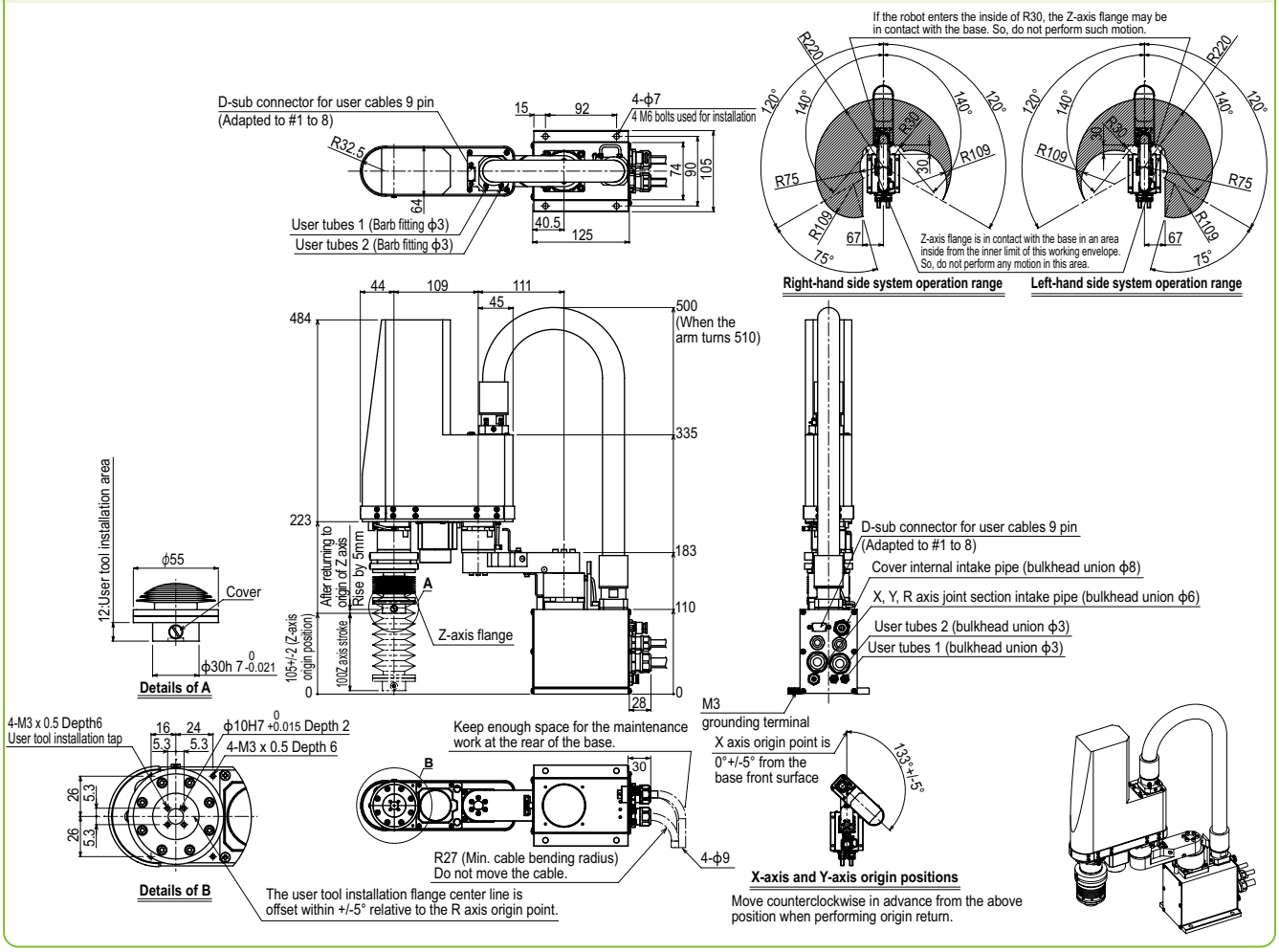
		X axis	Y axis	Z axis	R axis
Axis specifications	Arm length (mm)	111	109	100	–
	Rotation angle (°)	+/-120	+/-140	–	+/-360
AC servo motor output (W)		50	30	30	30
Repeatability Note 1 (XYZ: mm) (R: °)		+/-0.01		+/-0.01	+/-0.004
Maximum speed (XYZ: m/sec) (R: °/sec)		3.4		0.7	1700
Maximum payload (kg)		1.0			
Standard cycle time: with 0.1kg payload Note 2 (sec)		0.45			
R-axis tolerable moment of inertia Note 3 (kgm^2)		0.01			
User wiring (sq × wires)		0.1 × 8			
User tubing (Outer diameter)		ϕ3 × 2			
Travel limit		1.Soft limit, 2.Mechanical stopper (X, Y, Z axes)			
Robot cable length (m)		Standard: 3.5 Option: 5, 10			
Weight (kg) (Excluding robot cable) Note 4		6.5			
Robot cable weight		1.5kg (3.5m) 2.1kg (5m) 4.2kg (10m)			
Degree of cleanliness		CLASS 10 (0.1μm base)			
Intake air (Nℓ/min)		30			

Note 1. This is the value at a constant ambient temperature.
Note 2. When reciprocating 100mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. The total robot weight is the sum of the robot body weight and the cable weight.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

YK220XC



Controller RCX340 ▶ 678